## Analog Electronics Unit 9

# Unit 9. Power Supplies in analog systems

### Contents

### **1. Introduction**

- 2. Initial Stages (Transformer, Rectifier, Filter)
- **3. Classification**
- 4. Stabilized power supplies
- **5. Regulated power supplies**
- 6. Integrated power supplies
- 7. Decoupling capacitors
- 8. Non-symmetrical supply
- 9. Consumption calculation

## **1. Introduction**

### Electronic circuits need one or several DC voltage sources to operate correctly.

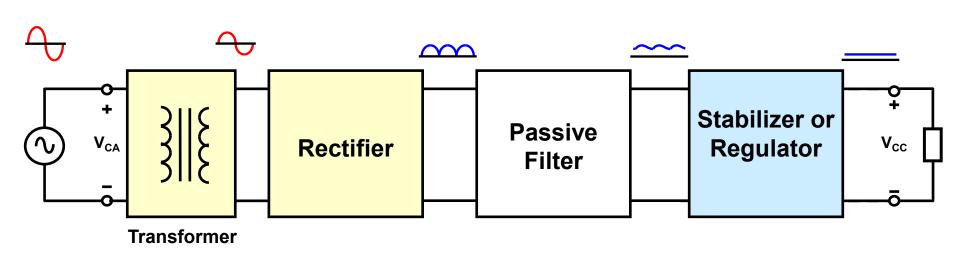
### Voltage supply with batteries:

- Low autonomy and high cost
- Acceptable for low consumption

### > Voltage supply from the net:

- The most common source of primary energy source
- Alternate sinusoidal voltage
- Net voltage must be converted to DC voltage

## **1. Introduction**



• Adapts voltage and current levels

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• Stabilizes the signal

## 2. Initial stages. Transformer

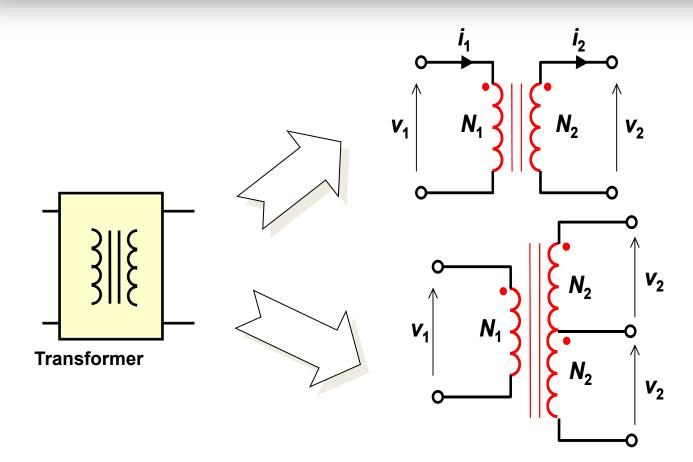
### ➤ Main functions:

- Adaptation of the net voltage to the value required by the load → N<sub>1</sub> : N<sub>2</sub>
- Provide galvanic isolation → Protection of the user

## Several configurations depending on the choosed rectifier:

- Primary-secondary
- Transformer with tapped secondary (toma intermedia)

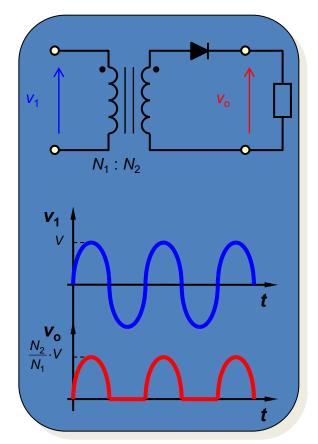
## 2. Initial stages. Transformer

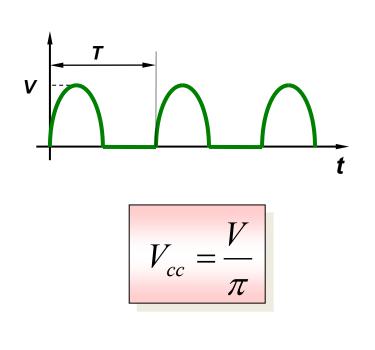


**v**<sub>2</sub> =  $\cdot V_1$ *i*<sub>2</sub>

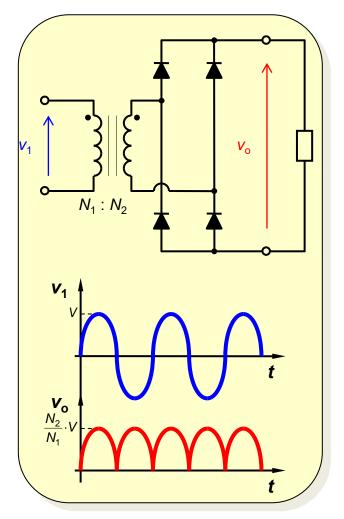
Converts tha AC voltage provided by the trafo into a pulsatory unidirectional voltage with a non-zero medium value.

### **Half-wave Rectifier**



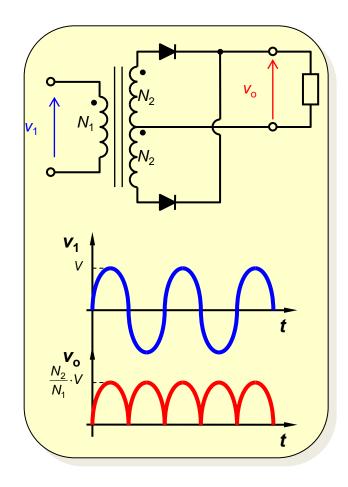


### **Full-wave Rectifier: Diodes bridge.**

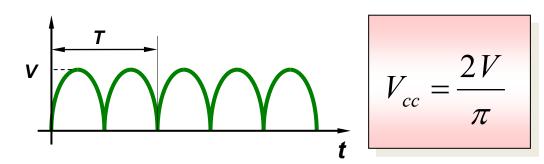


- During each hemicycle 2 diodes conduct simultaneously.
- Each diode supports an inverse voltage of the maximum voltage value of the secondary.
- This configuration is the most common.

### Full-wave Rectifier: with tapped secondary



- During each hemicycle only one diode conducts.
- Each diode supports an inverse voltage of the double of the maximum voltage value of each winding of the secondary.



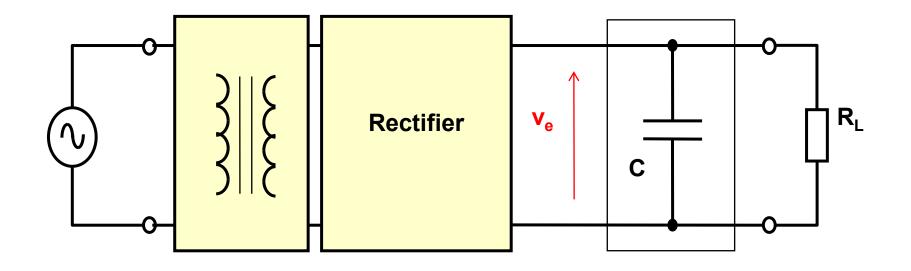
The selection of the diodes depends on the voltages and currents required in the specific application.

- Average forward current, I<sub>F(AV)</sub>
- Peak working reverse voltage, V<sub>RWM</sub>
- Repetitive forward peak current, I<sub>FRM</sub>

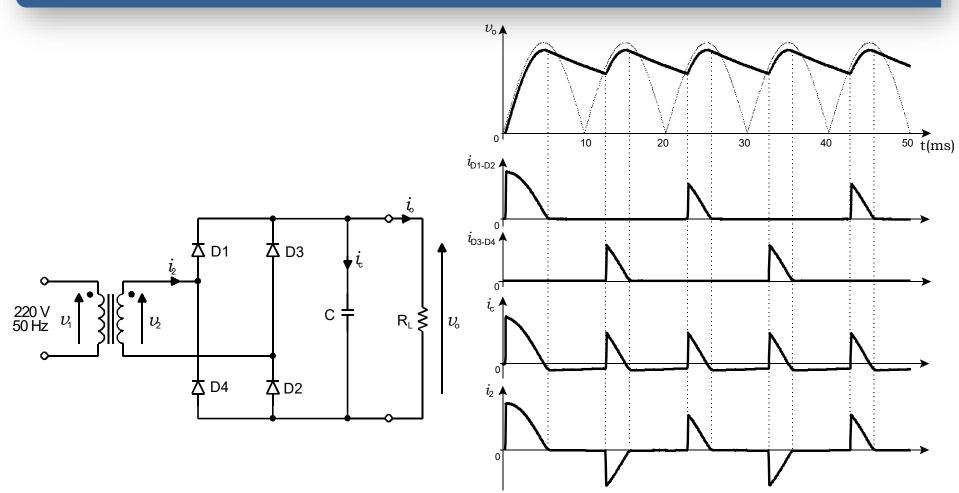
#### "General purpose" diodes are commonly used.

- Designed to work at low frequencies in rectification applications (< 400 Hz).
- They can support currents of 1 to 25 A, with reverse voltages of 50 to 1000 V.
- Rectifying bridges with 4 diodes are also available as integrated circuits.

## 2. Initial stages. Filter



## 2. Initial stages. Filter



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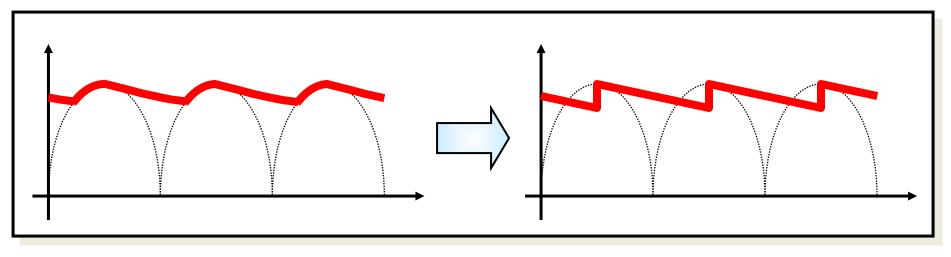
## 2. Initial stages. Filter

### > Output voltage: exponential and sinusoidal

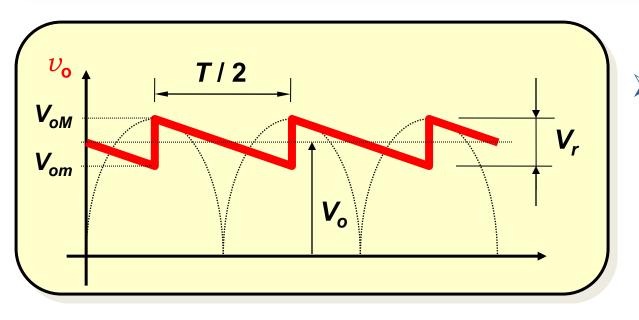
• The detailed analysis is complex

### > Aproximation to a triangular waveform -> simplification

- Considers a lineal discharge of the capacitor (RL·C>>T/2)
- Supposes an instantaneous charge of C when the diodes conduct

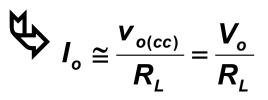


## 2. Initial stages. Filter



Supposes discharge of C at constant current.

$$i_{C} = i_{load} = I_{o}$$

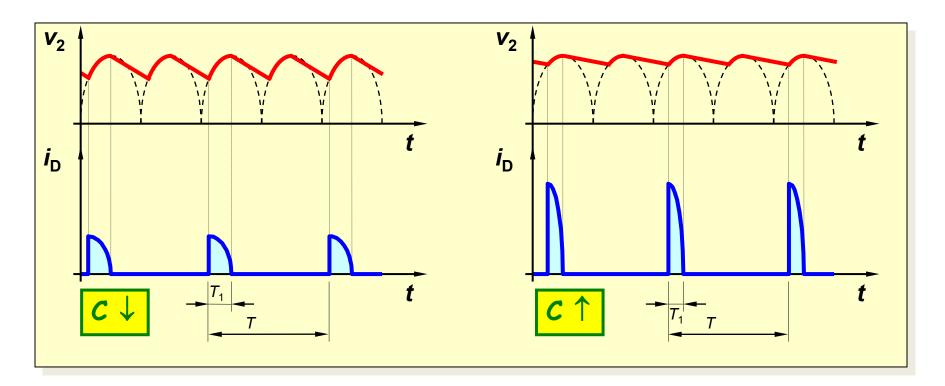


## The value of Vr is usually known Limited by the specifications

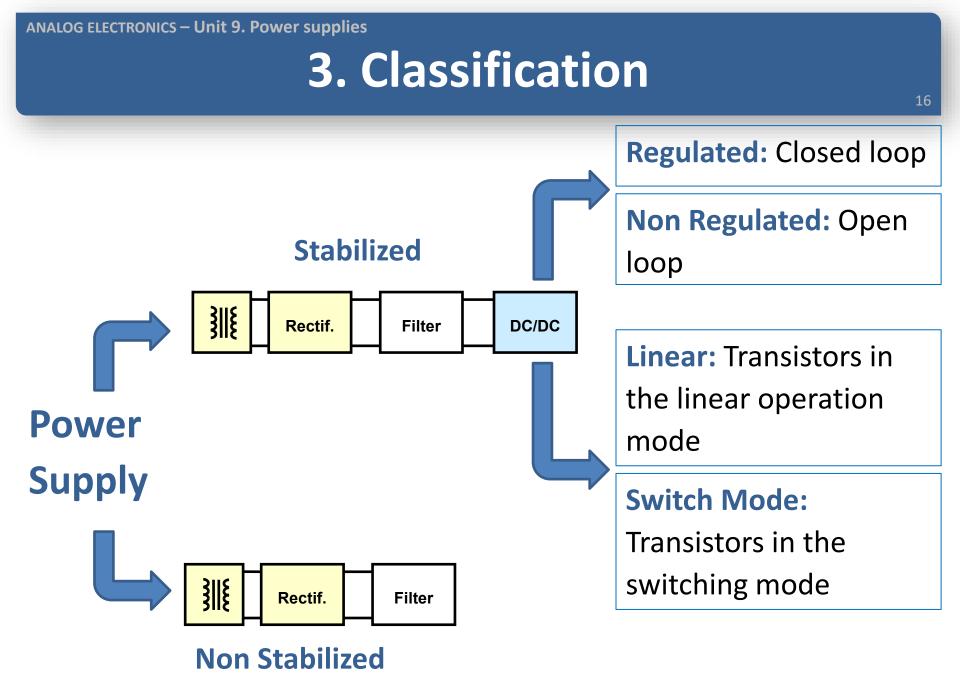
- Allows the calculation of C
- Tolerances must be considered (±20%)

$$V_r = \frac{V_o}{2 f R_L C} = \frac{I_o}{2 f C}$$

## 2. Initial stages. Filter

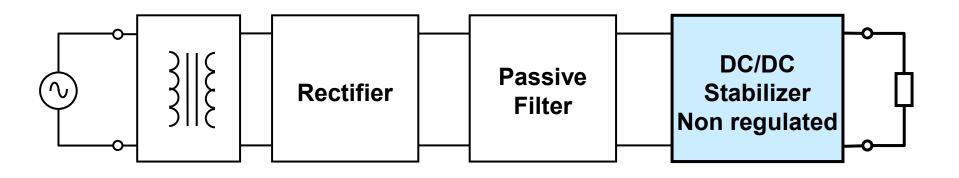


$$I_{D(peak)} \cong \frac{T}{T_1} I_{dc}$$

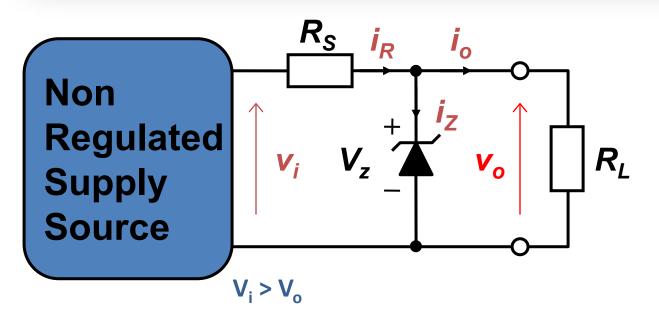


## 4. Stabilized Power Supplies

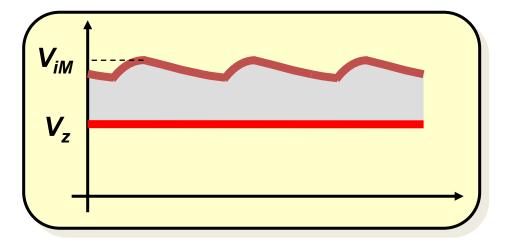
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## 4. Stabilized Power Supplies



$$v_o = V_z$$

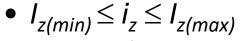


## The difference of both voltages is supported by R<sub>s</sub>

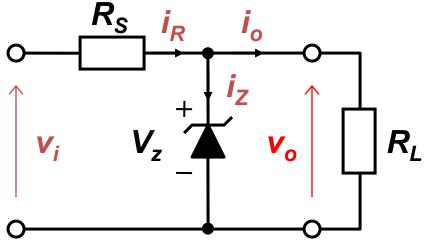
- v<sub>i</sub> should not be much higher than v<sub>o</sub>. Vo=ViRL/(Rl+Rs)>Vz
- Election of  $N_2:N_1$ .

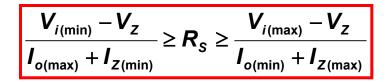
## 4. Stabilized Power Supplies

### Operation Limits



• Current in  $R_S$ :  $I_{R(min)} = I_{o(max)} + I_{Z(min)}$ 





### **R**<sub>s</sub> should be big enough:

- Less warming up of the zener
- V<sub>o</sub> is less affected by fluctuations in V<sub>i</sub>

### Main drawback:

 If the circuit is designed for high I₀, the zener diode should support such currents → power zener diode

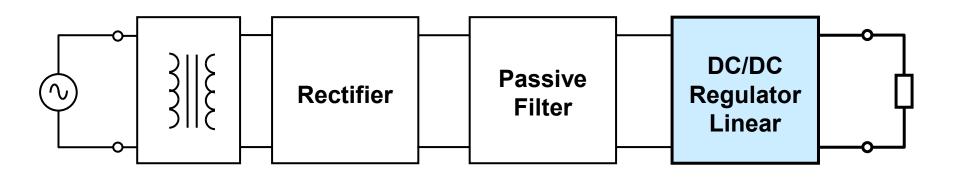
## **5. Regulated Power Supplies**

### Limitations of stabilizing circuits:

- The accuracy of the output voltage depends on the features of the used electronic devices.
- Lack of control of the output voltage.

## Linear Regulator → mantains constant the output voltage

• System with negative feedback to mantain constant the output voltage when the load or the input voltage variates.



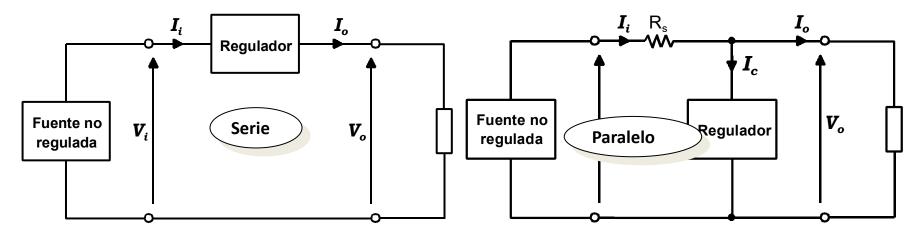
## **5. Regulated Power Supplies**

### > Two kinds of regulators: series and shunt

Variations in the output voltage provoked by changes in the nonregulated voltage and in the output current are compensated by variations in:

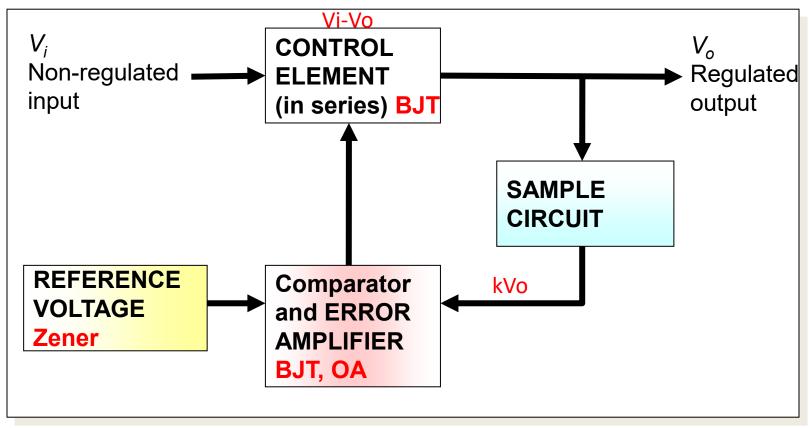
- •The voltage drop of an element situated in series with the load **> Series Regulator** (the most common)
- •The current of an element situated in parallel with the load

### Shunt Regulator



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### **Blocks diagram of a serie regulator:**



Feedback:  $\uparrow V_o \rightarrow control \uparrow (V_i - V_o) \rightarrow \downarrow V_o$ 

### **Reference circuit:**

- Provides a stable reference voltage.
- Usually based on a zener diode.
- Simplest solution → zener diode + polarizing resistor.

### Sample circuit:

- Provides a signal proportional to the output signal.
- Usually composed by a resistor divider connected to the output.

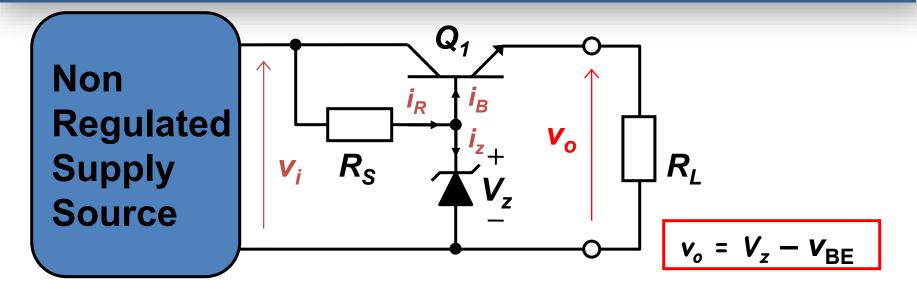
### **Error amplifier:**

• Compares the sampled voltage with the reference voltage and generates an error signal proportional to the difference.

### **Control element:**

- Recieves the error signal and corrects the variations of the output voltage.
- Is usually composed by a bipolar transistor (NPN usually) connected in series between the input and output of the regulator.

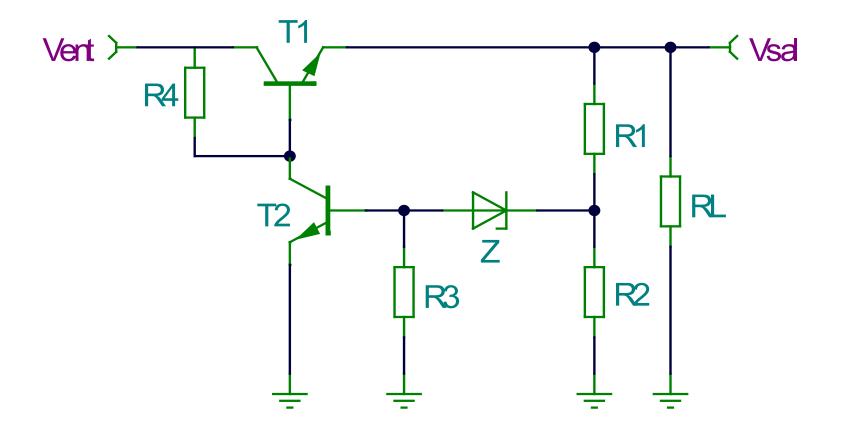
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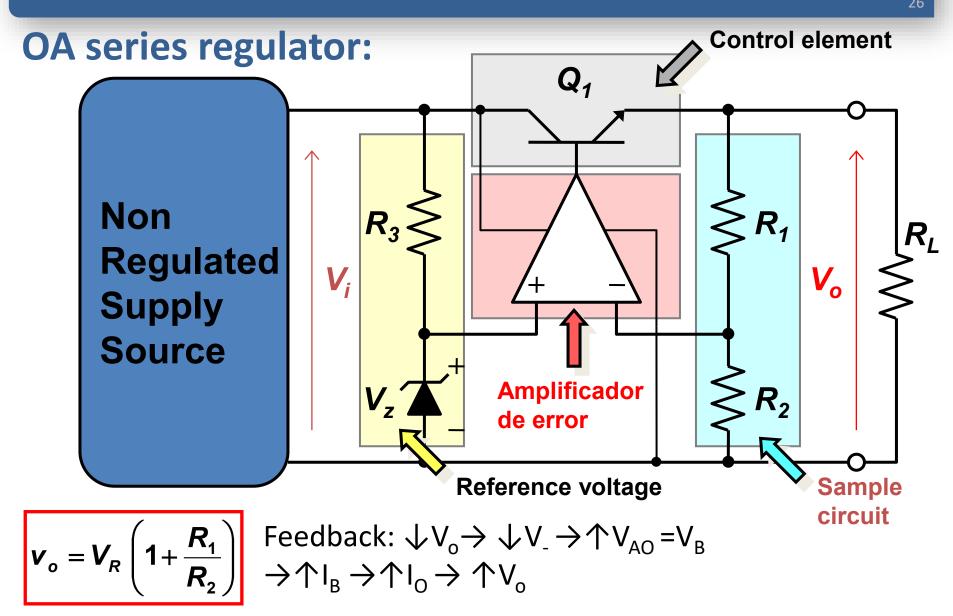


• The transistor dissipates the power generated by  $v_i - v_o$ .

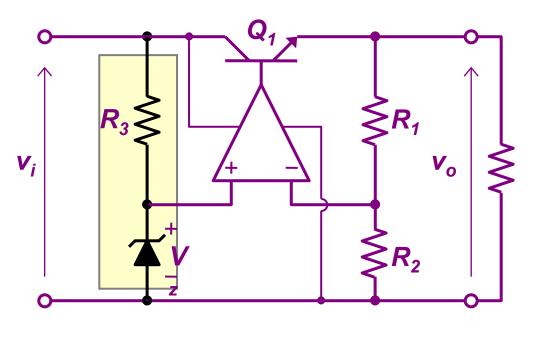
• Design of 
$$R_S \rightarrow R_{S(max)} = \frac{V_{i(min)} - V_Z}{I_{Z(min)} + \frac{I_{o(max)}}{\beta + 1}}$$

• The zener diode does not need to support elevated currents. Feedback:  $\uparrow V_o \rightarrow \downarrow V_{BE} \rightarrow \downarrow I_E = (1+\beta)I_{ss}e^{VBE/VT} \rightarrow \downarrow I_o \rightarrow \downarrow V_o$  **P50.** En el circuito de la figura calcular: a) Tensión de salida que fija el regulador en la carga  $R_L$ b) Tensión y corriente en cada una de las resistencias del circuito. Datos: R1 = 3.3 k $\Omega$ , R2 = 2.2 k $\Omega$ , R3 = 5 k $\Omega$ , R4 = 10 k $\Omega$ , RL = 2 k $\Omega$ Vent = 40 V, V<sub>z</sub> = 10 V. Para T1 y T2: V<sub>BF</sub> = 0.7 V,  $\beta$  =100





### **OA series regulator:**



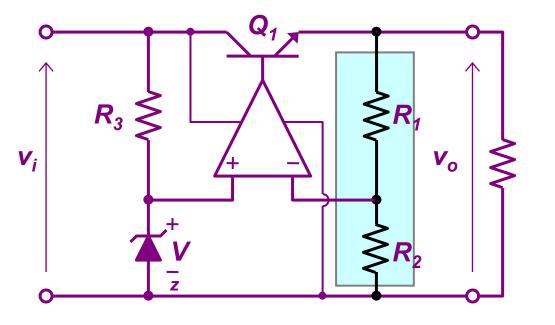
### **Reference Voltage:**

- Simple circuit.
- Select R<sub>3</sub> high enough to reduce the effect of the ripple of v<sub>i</sub>.

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 Also LEDs, rectifying diodes, IC reference circuits (LM336).

### **OA series regulator:**



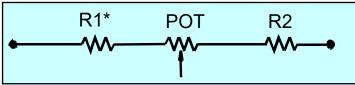
### Sample circuit

- Very simple circuit.
- The supported current must be negligible versus the load current.

 $R_1$  and  $R_2$  high values compared to the load.

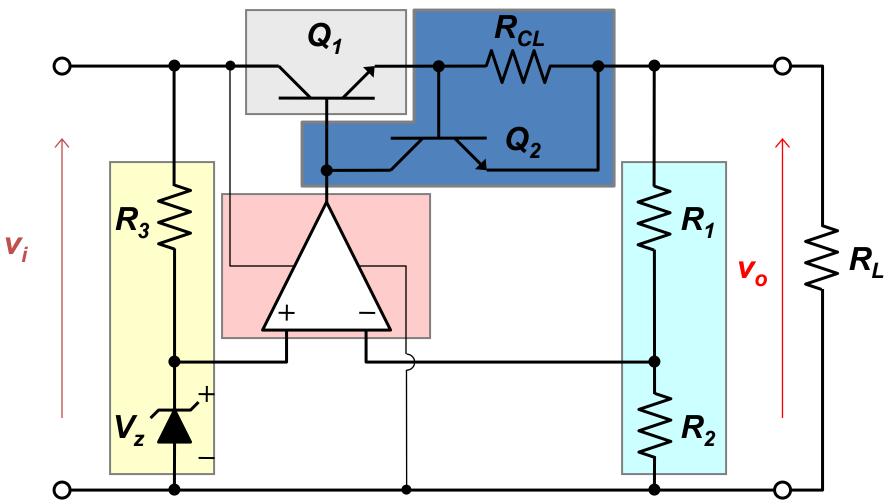
#### To allow Vo adjustment:

A potentiometer should be used in the voltage divider.



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### **OA series regulator: current limitation**



### **OA series regulator:**

### Limitation at constant current.

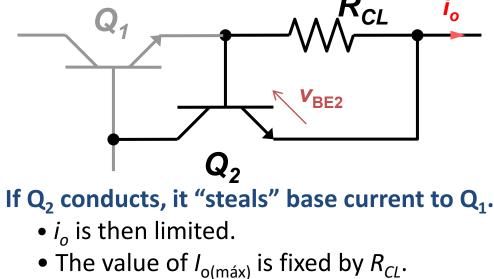
• If  $i_o > I_{o(max)}$ ,  $v_o$  decreases  $\rightarrow 0 \le v_o \le v_{o(nom)}$ .

• If  $i_o < I_{o(max)}$ , then  $v_o = v_{o(nom)}$ .

$$I_{o(\max)} = I_{SC} = \frac{V_{BE2(ON)}}{R_{CL}}$$

Regulation curve

In shortcircuit:  $P_{Q1} \approx v_i \cdot I_{o(max)}$ 

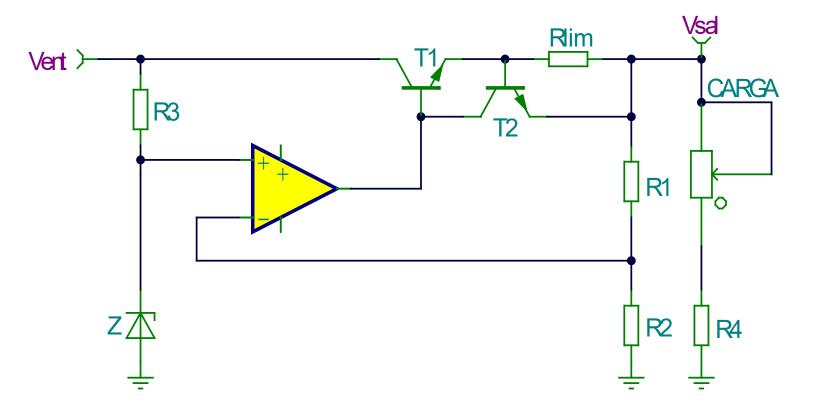


**P52.** En el circuito de la figura calcular:

- a) Tensión de salida que fija el regulador
- b) Corriente en la resistencia R3
- c) Corriente mínima y máxima en la resistencia R4.
- d) Calcular la resistencia limitadora Rlim
- Podemos despreciar las corrientes por R1 y R2 para facilitar los cálculos.

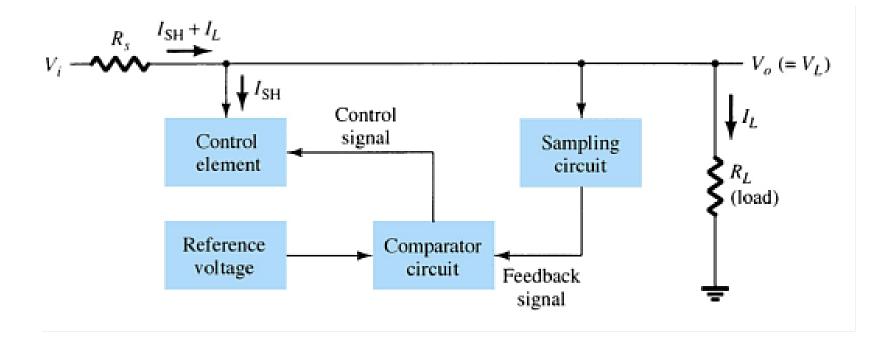
Datos:  $R1 = 100 \ k\Omega$ ,  $R2 = 50 \ k\Omega$ ,  $R3 = 5 \ k\Omega$ ,  $R4 = 50 \ \Omega$ ,  $POT = 0.55 \ k\Omega \ / \ 3 \ W$ 

 $Vent = 35 V, V_Z = 10 V, I_{Zmin} = 1 mA, P_{Zmax} = 0.5 W, V_{BE} = 0.6 V$ 



## 5. Regulated Power Supplies. Shunt.

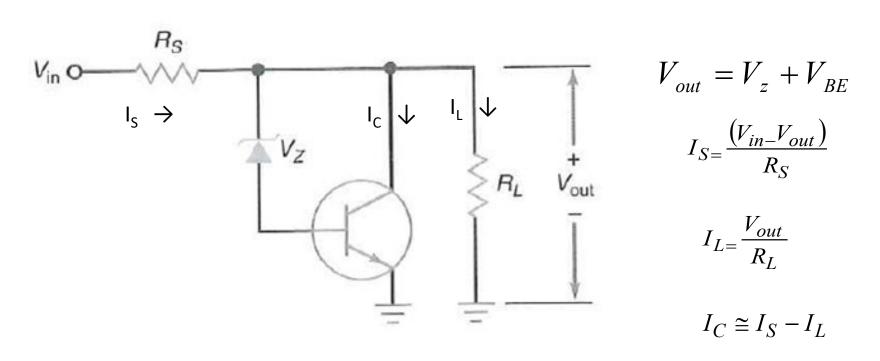
### **Shunt regulator:**



Feedback:  $\uparrow V_{o} \rightarrow control \uparrow I_{SH} \rightarrow \downarrow I_{L} \rightarrow \downarrow V_{o}$ 

## 5. Regulated Power Supplies. Shunt.

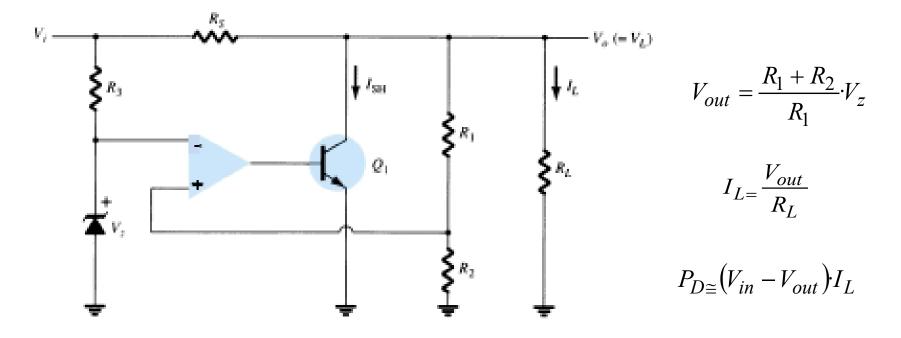
### **Shunt regulator:**



Feedback:  $\bigvee R_L \rightarrow \bigvee V_0 \rightarrow \bigvee V_{BE} \rightarrow \bigvee I_Z \rightarrow \bigvee I_C \rightarrow \uparrow I_L \rightarrow \uparrow V_0$  $V_0$  remains constant ( $R_L$  fluctuations compensated by  $I_L$  fluctuations)

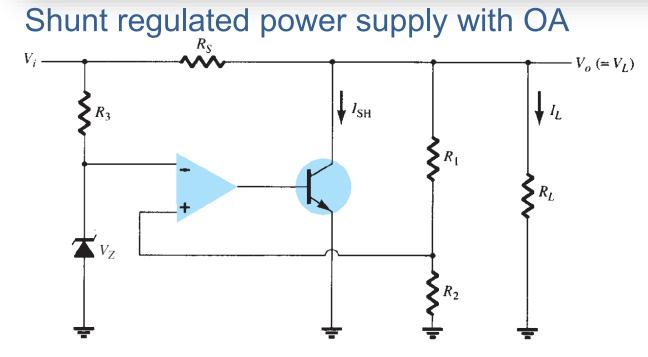
## 5. Regulated Power Supplies. Shunt.





 $\mathsf{Feedback:} \downarrow \mathsf{V_o} \rightarrow \downarrow \mathsf{V_+} \rightarrow \downarrow \mathsf{V_{AO}} = \mathsf{V_B} \rightarrow \downarrow \mathsf{I_{SH}} \rightarrow \uparrow \mathsf{I_L} \rightarrow \uparrow \mathsf{V_o}$ 

## 5. Regulated Power Supplies. Shunt.



**Exercise.** OA (741C,  $\pm$ 15 V, Io-max=25 mA), Rs=1.5  $\Omega$ , Vi=20-22 V, IL=0.8-1.2 A, Vz=5 V, BJT( $\beta$ =100-400, Vbe-on=0.65 V) 1) Design R1 and R2 for Vo=18 V. Calculate: 2) Range of ISH and check the non-saturation of the OA. 3) Maximum power in Rs and BJT.

## 6. Integrated Power Supplies

### They appeared because of the need of regulators in the power supplies.

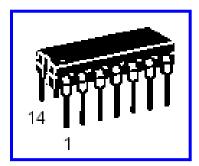
- First generation → components of general application.
- The big demand of specific voltage supplies (5V for instance) led to the manufacturing of fixed voltage regulators with only 3 terminals.
- Low cost, easy to use.
- Later voltage regulators with 3 terminals but with adjustable voltage were developped.
  - •Low cost + easy to use + versatility.

### **Classification:**

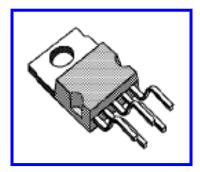
- Regulators of multiple terminals.
- Regulators of 3 terminals:
  - fixed voltage:
    - positive
    - negative
  - adjustable voltage:
    - positive
    - negative

### **Regulators of multiple terminals**

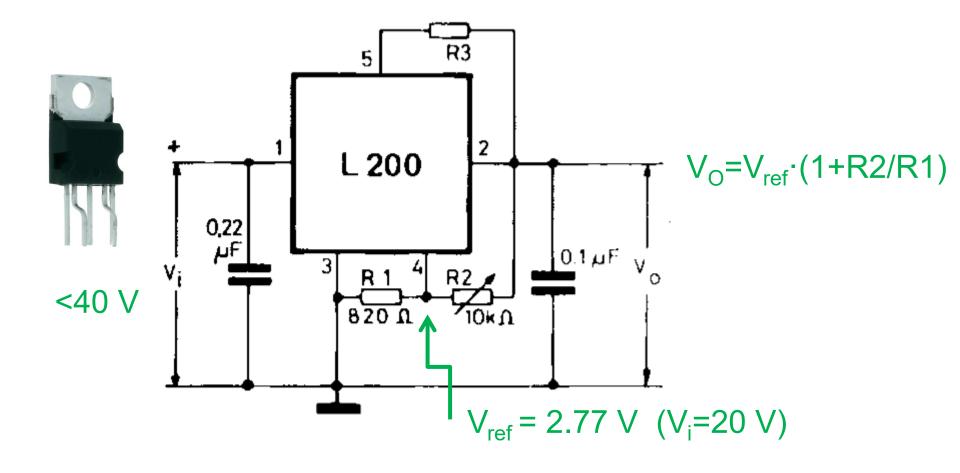
- Based on the linear basic regulator.
- Several parts of the circuit are independent and can be connected by the user.
- Most representative examples:
  - µA723 (14 terminales)



#### • L200 (5 terminales).



### **Regulators of multiple terminals: L200**



NC

FC

V+

V<sub>c</sub>

٧,

Vout

14

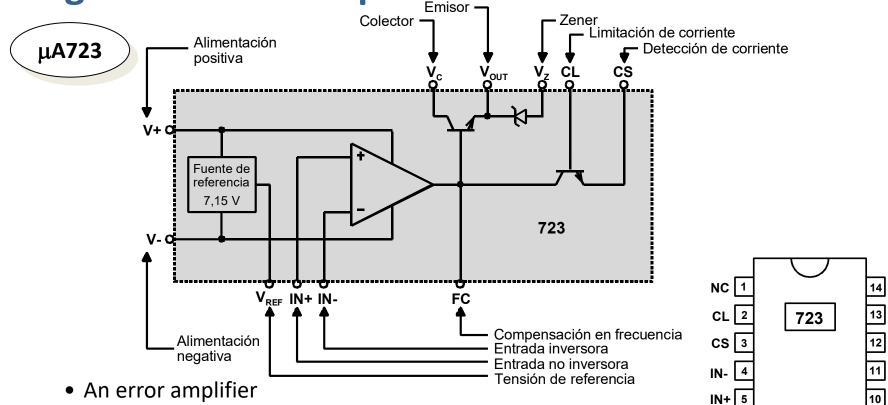
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8 NC

V<sub>REF</sub>6

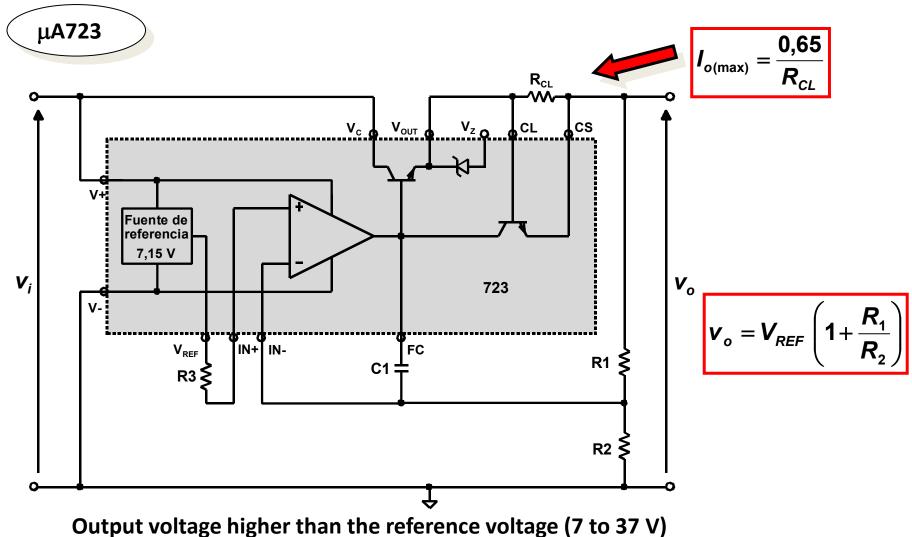
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### **Regulators of multiple terminals**



- A reference voltage source
- A transistor as control element
- A transistor to limit current
- A zener diode for specific applications
- A terminal for frequency compensation

### **Regulators of multiple terminals**



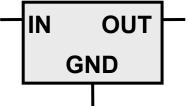
### **Regulators of 3 terminals**

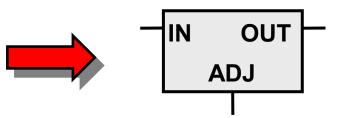
- Regulated output.
- Simple use and low cost.

> Two types:

- •**Fixed regulators:** provide a fixed voltage (positive or negative).
- •Adajustable regulators: the output voltage (positive or negative) can be adjusted using external components.







### **Regulators of 3 terminals**

- Regulators 78XX provide positive voltages, whereas 79XX provide negative voltages.
- The last 2 digits XX, indicate the output regulated voltage.

I <sub>o(max)</sub> (A)
0,1
0,5
1
3

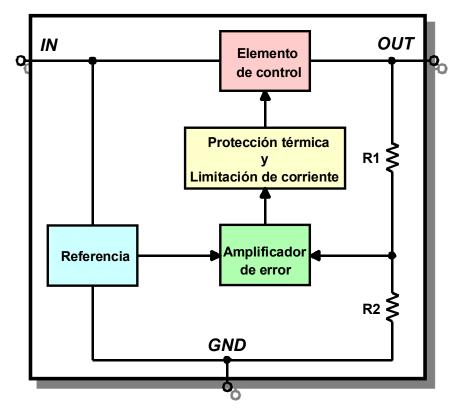
Тіро	V <sub>o</sub> (V)	V <sub>i(min)</sub> (V)	V <sub>i(max)</sub> (V)		
7805	5	7	35		
7806	6	8	35		
7808	8	10	35		
7809	9	11	35		
7810	10	12	35		
7812	12	14	35		
7815	15	17	35		
7818	18	20	35		
7824	24	26	40		
79XX Same values but negative					

- Datasheets:
  - •LM78XX ⇒ National Semiconductor, Fairchild.
  - •UA78XX ⇒ Texas Instruments
  - •MC78XX ⇒ Motorola, ON Semiconductors,...

### **Regulators of 3 terminals**

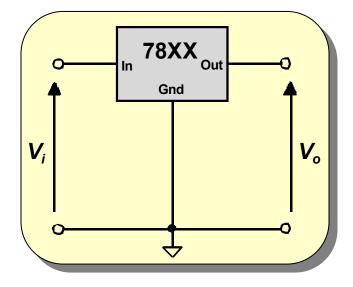
# Linear basic regulator with additional elements:

- Limitation of the maximum output current as a function of the difference in inputoutput voltage → power limitation.
- Thermic protection → the control element can be disconnected.
- Error amplifier internally compensated
- Reference voltage of low noise and high stability.



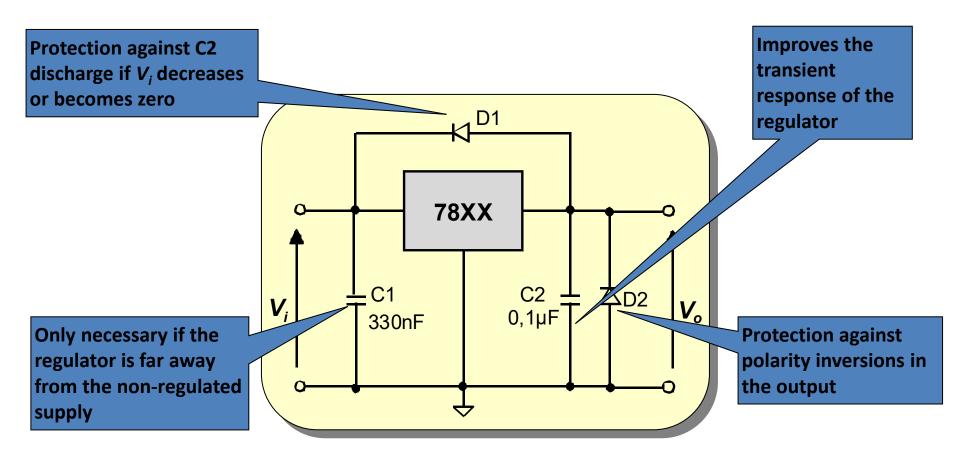
### **Regulators of 3 terminals. Positive.**

- No external element is needed.
- The input is provided by a non-stabilized voltage supply or by a DC supply.
- The input voltage must be higher than the output, at least 2 or 3V.

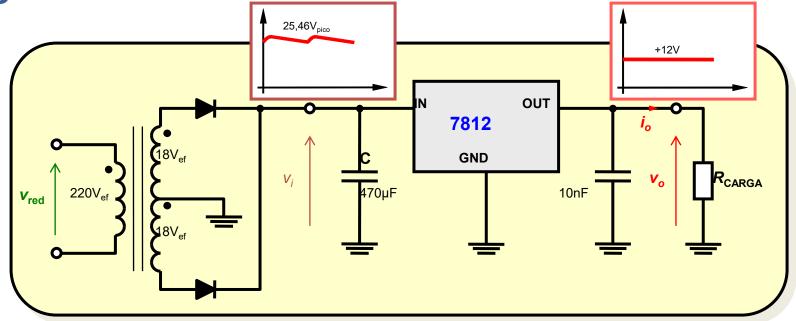


### **Regulators of 3 terminals. Positive.**

External elements can be added:



### **Regulators of 3 terminals.** Positive.



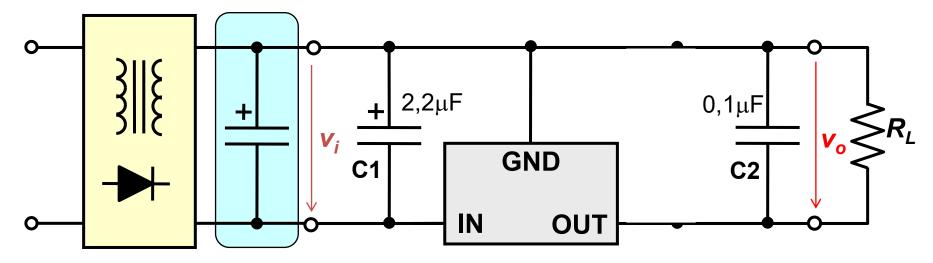
- The selection of N2:N1 is important to minimize the power dissipation.
- The capacitor C assures that v<sub>i</sub> never decreases under a specific value.
  - The discharge or output current is *i*<sub>o</sub>.

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### **Regulators of 3 terminals. Negative.**

### ≻Series 79XX.

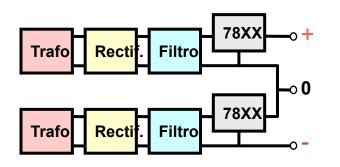
- Similar to the positive regulators 78XX.
- The capacitor in the output assures the stability.
- As in 78XX, C1 is only necessary if the regulator is far away from the filter. C3 improves the transient response.
- <u>All capacitors</u> associated to the regulator should be connected as near as possible from the regulator.

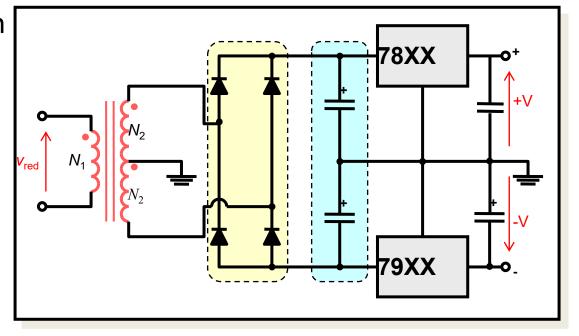


### **Regulators of 3 terminals.**

### > They simplify the implementation of symmetric supply sources.

This could be achieved with 2 different 78XX, but 2 complete supply sources would be needed:



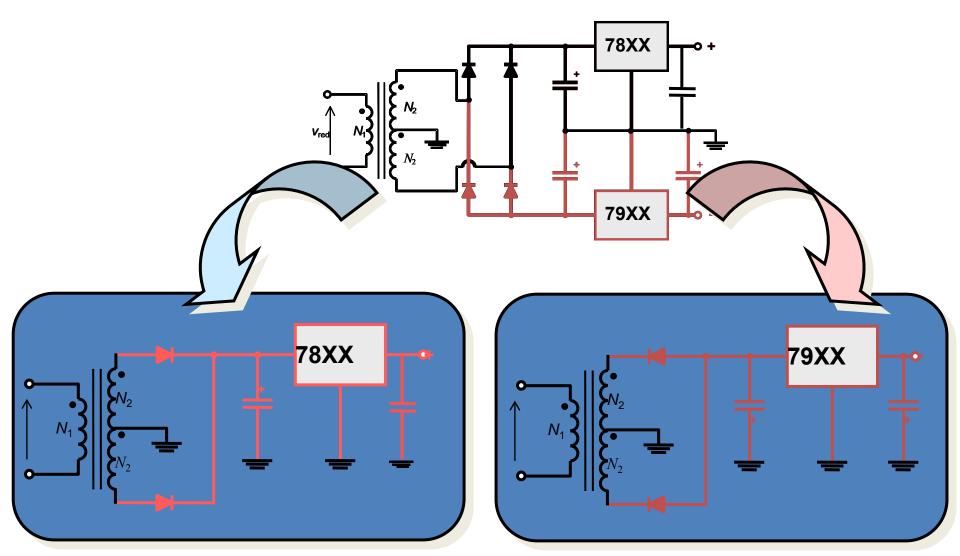


Using 79XX the design is simpler

**ANALOG ELECTRONICS – Unit 9. Power supplies** 

### 6. Integrated Power Supplies

### **Regulators of 3 terminals.**



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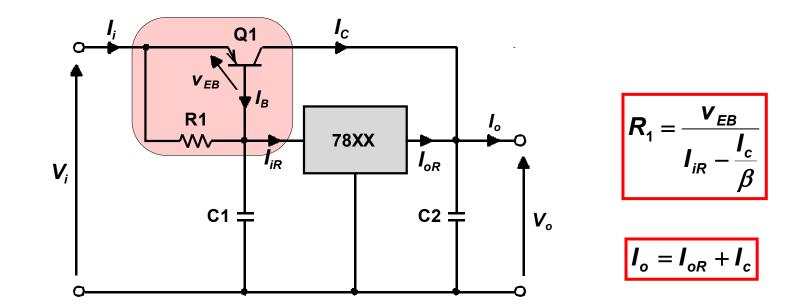
### **Regulators of 3 terminals.** Increase of the output current.

#### >Addition of a transistor and a resistor to increase the output current.

- Transistor  $\rightarrow$  supports most of the current supplied to the load.
- Regulator  $\rightarrow$  assures the stability of the output voltage.

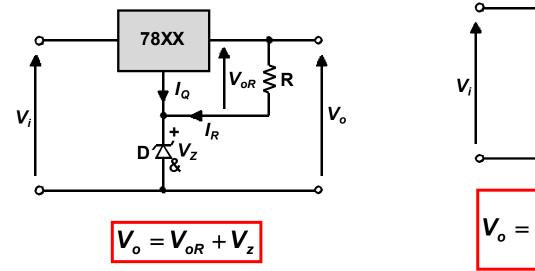
#### > The minimum difference of input-output voltage increases.

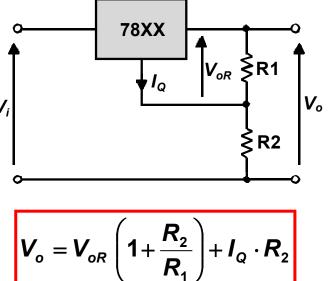
•  $v_{EB}$  + minimum voltage drop in the regulator (2 or 3 V).



### **Regulators of 3 terminals.** Increase of the output voltage.

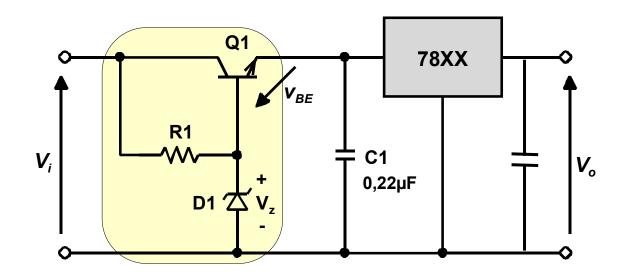
- With a fixed regulator a different output voltage (from the nominal one) can also be obtained.
- Addition of a positive voltage to the reference terminal (Gnd/Common) of the regulator.
  - The quiescent current (8.5 mA maximum) must be assured.



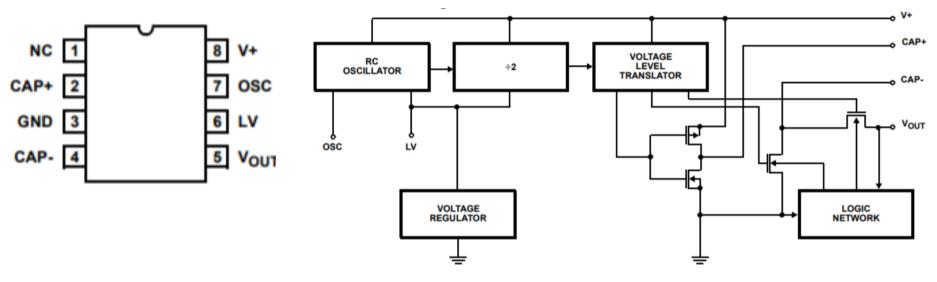


### **Regulators of 3 terminals.** Elevated input voltages.

- ➢In general, the maximum input voltage for a 78XX is 35 V (for 79XX, -35 V).
- ➢If the input voltage is higher, a stabilizer can be connected before the regulator.
- >This solution helps to dissipate less power in the regulator.

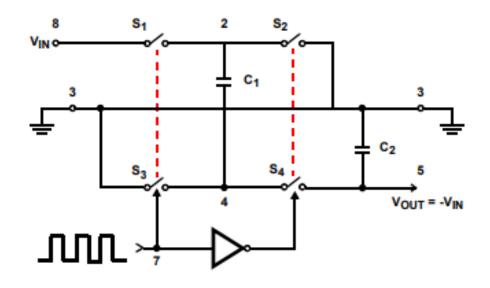


### **Voltage Converters: ICL7660**

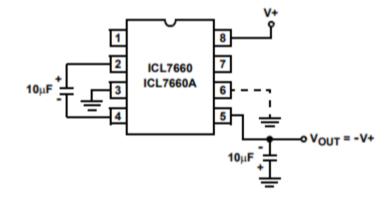


 CMOS power supply circuits
 Supply voltage conversions: +1.5V to +10.0V
 Voltage doublers

**Voltage Converters: ICL7660 as negative converter** 

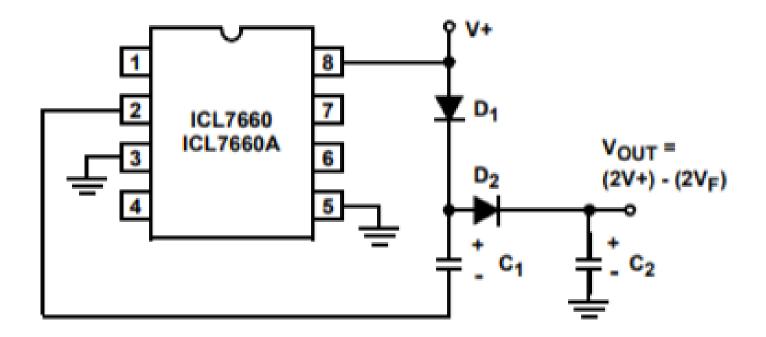


CMOS Switches: S1, S3 charge of C1 to Vin S2, S4 Vout=-Vin



Simple negative converter Pin 6 to ground only if V+ < 3.5V

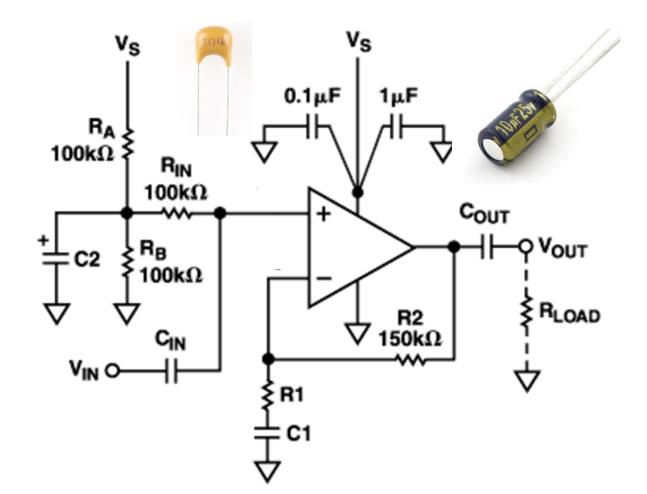
### Voltage Converters: ICL7660 as voltage doubler



 $V_{\rm F}$  forward voltage of the diode

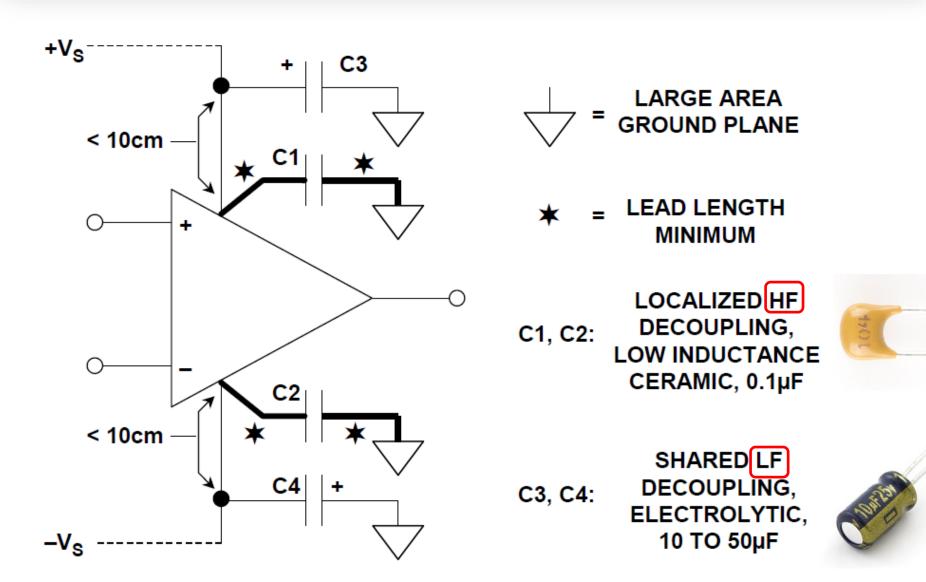
# 7. Decoupling capacitors

### They operate as charge reservoir (decoupling)

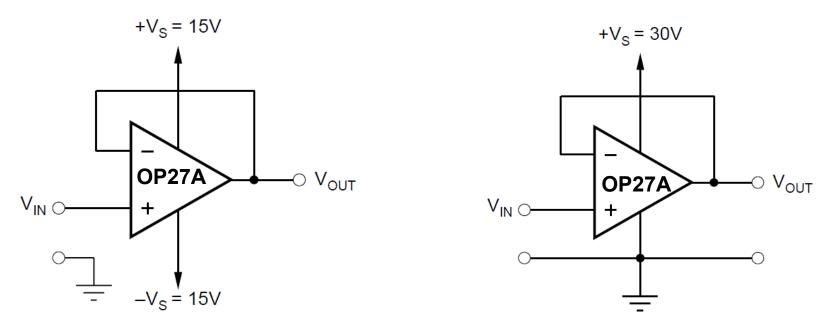


**ANALOG ELECTRONICS – Unit 9. Power Supplies** 

### 7. Decoupling capacitors



Work out the voltage range at the output V<sub>OUT</sub>



<b>OP27</b> $\begin{array}{l} \text{SPECIFICATIONS} \\ \text{ELECTRICAL CHARACTERISTICS} \\ V_s = \pm 15 \text{ V},  T_A = 25^{\circ}\text{C}, \text{ unless otherwise noted.} \end{array}$							Data	Sheet		
				OP	27A/OP2	27E		OP27G		
Parameter		Symbol	Test Conditions	Min	Тур	Мах	Min	Тур	Мах	Unit
OUTPUT VC	DLTAGE SWING	Vo	$R_L \ge 2 k\Omega$	±12.0	±13.8		±11.5	±13.5		V

±10.0

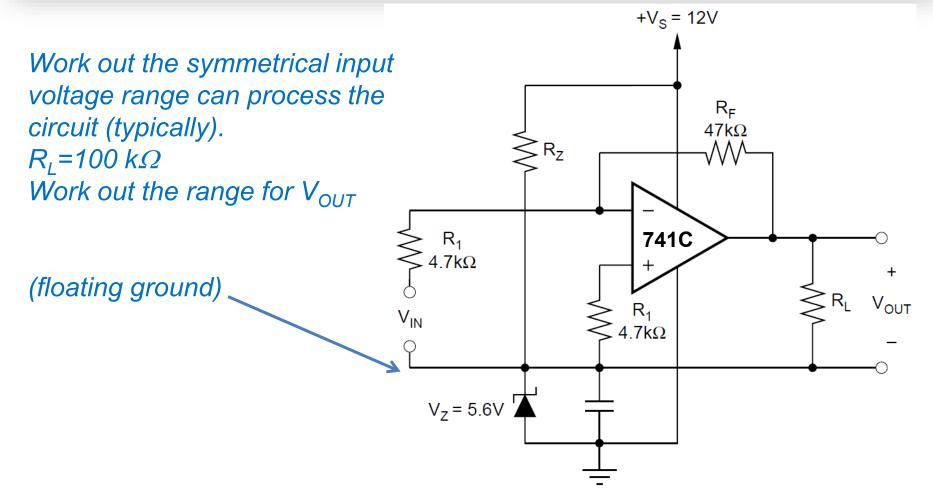
±11.5

 $R_L \ge 600 \Omega$ 

V V

±10.0

±11.5

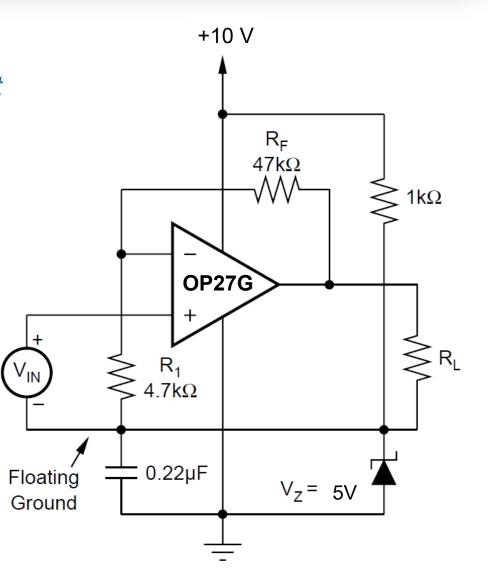


#### **Electrical Characteristics, LM741C**

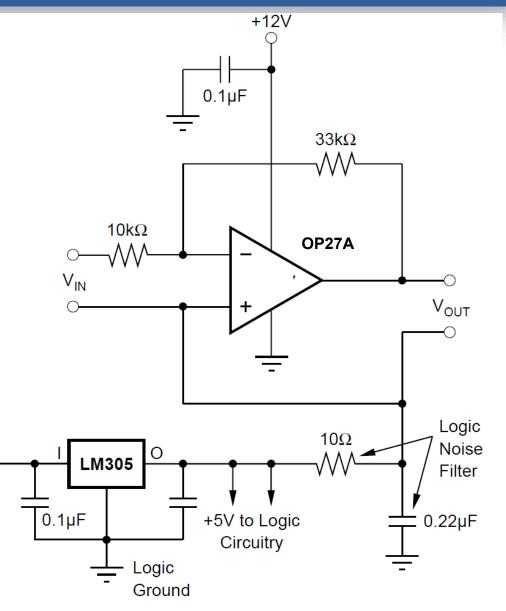
PARAMETER	TEST CO	MIN	TYP	MAX	UNIT	
Output voltage swing	V <sub>S</sub> = ±15 V	R <sub>L</sub> ≥ 10 kΩ	±12	±14		- V
		R <sub>L</sub> ≥ 2 kΩ	±10	±13		

Work out the symmetrical input voltage range can process the circuit (typically).  $R_L$ =100 k $\Omega$ Work out the range for V<sub>OUT</sub>

Work out the current in the zener diode



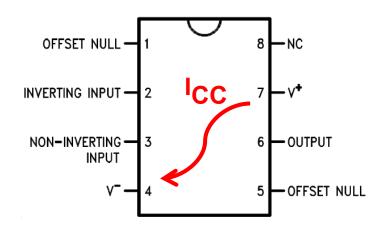
Estimate the gain of the system  $(V_{OUT}/V_{IN})$  and the maximum range at the input (typical values)



The OA supply is +15 V, work out the voltage at the output of the OA. What is the role of  $C_{IN}$ , C1 and  $C_{O}$ ? (coupling capacitors, DC biasing)  $R_{f}$ Work out the range of  $V_{IN}$ 100k CIN **R1** 10k Co 741C ۷o VIN R<sub>B</sub> RL 6.2k 10k **R2** 100k **R3** 100k **C1**  $10\mu F$ 

**ANALOG ELECTRONICS – Unit 9. Power Supplies** 

# 9. Consumption estimation



#### **Absolute Maximum Ratings**

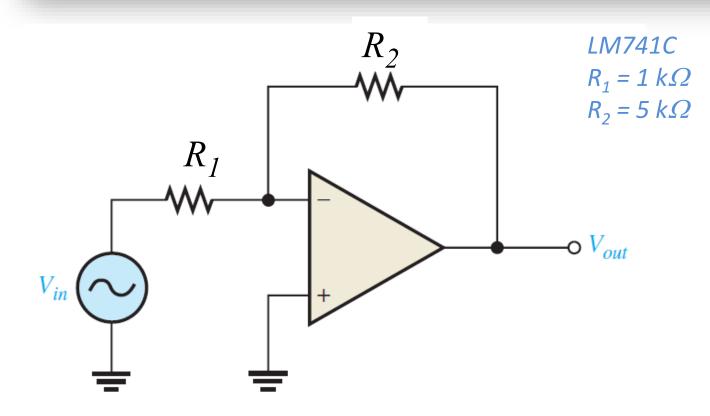
		MIN	MAX	UNIT
Supply voltage	LM741, LM741A		±22	V
	LM741C		±18	V
Power dissipation <sup>(4)</sup>			500	mW

#### **Electrical Characteristics, LM741C**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Supply current	T <sub>A</sub> = 25°C		1.7	2.8	mA
Power consumption	$V_{S} = \pm 15 \text{ V}, \text{ T}_{A} = 25^{\circ}\text{C}$		50	85	mW

#### **ANALOG ELECTRONICS – Unit 9. Power Supplies**

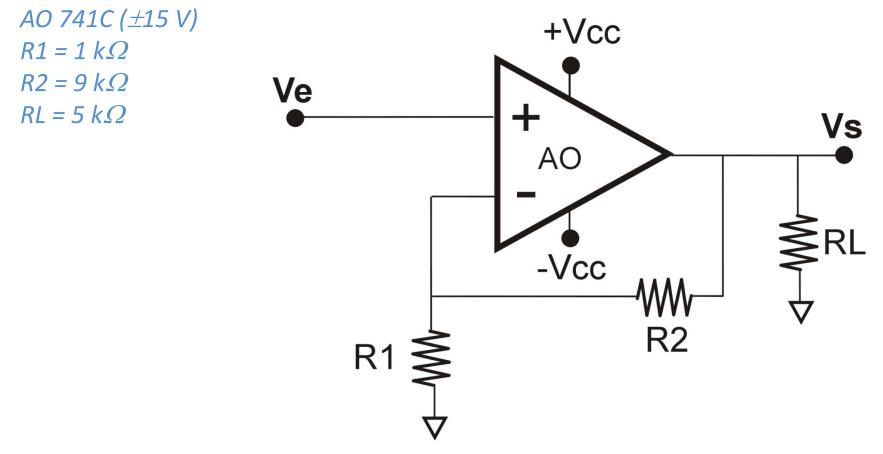
### 9. Consumption estimation



Estimate the current supplied by each supply source when the OA is supplied with  $\pm 15$  V and Vin = +2 V Estimate the power dissipated by the OA. Is the maximum power exceeded? Repeat the calculations when the supply is +30 V and Vin = -2 V

## 9. Consumption estimation

If the input voltage Ve varies between ±1 V, estimate:
1) Maximum current consumption (provided by the supply source)
2) Maximum power dissipated by the OA. Check that the maximum power is not exceeded.



# 9. Consumption estimation

*If the input voltage Ve = –2 V, estimate:* 

1) Maximum current consumption (provided by the supply source)

2) Maximum power dissipated by the OA. Check that the maximum power is not exceeded.

*3) Check that the balance of dissipated powers and provided by all the components of the circuit.* 

